## **Over Current Relay**

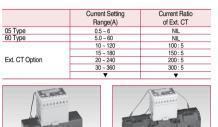
#### Option-1. Looping (Protect smaller current by looping option)

Some motor size may require one-third or one-fourth of particular EOCR current range. These installations can be accommodated by looping the motor wire 2 or 3 times through the integral current transformers of the EOCR. This reduces the number and type of relays inventoried for spare purposes. Each additional loop will increase the current measured as indicated by the following chart.



Line

Option-2. External Current Transformer Option (Ext. CT option protect bigger current) Ordering option - 05 type of each model fitted to an external current transformer can achieve higher amnere ranges



External 3CT Option External SR-CT Option

### EOCR Type Table for 3phase Motor

aight-through-Wiring

Fia 1

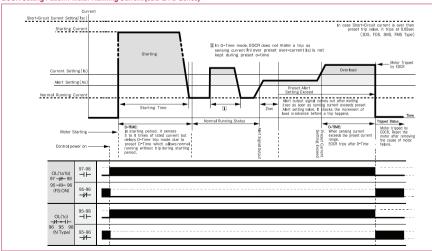
Line

Current Setting Range			Capacity of 3 Pha	se Motor	(kW/HP)			Cable	e Size	
(Adjustable)	AC22	20(V)	Current	AC380	/440(V)	Current	TYPE	Thickness	Allowable	Remark
(A)	kW	HP	(A)	kW	HP	(A)		(hm)	Current(A)	
0.5 ~ 6	0.75	1	4.8	1.5	2	4.2/3.6	05	3.5	28	
5.0 ~ 60	5.5	7.5	26	22	30	49 / 46	60	5.5~14	67	Built-in CT(Standard type)
10 ~ 120	22	30	93	37	50	84/73	100:05	38	130	
20 ~ 240	37	50	160	75	100	163 / 141	200:05	100	240	Assemble
30 ~ 360	55	75	230	132	175	263 / 227	300:05	250	430	with
40 ~ 480	95	125	360	190	250	376 / 325	400:05	325	495	External CT
50 ~ 600	110	150	440	220	300	423 / 390	500:05	400	565	LAIGHIGIUT
60 ~ 720	150	200	570	300	400	602 / 520	600:05	500	625	

oing Option (2-Loop)

Fia 2

### EOCR Setting Patlem / Motor Running Current (3DD & FD Series)



### Overview

### D-TIME(Delay Time):

When starting the motor, it's current is increasing 5 to 8 times of rated current and its starting time is different according to the load of motors. D-Time knob(Mode) has a function to delay the trip during starting period even if starting current exceeds over preset over-current value.

### O-TIME (Operating Delay Time):

When EOCR senses over-current which exceeds over preset over-current range O-Time knob(Mode) delays trip until EOCR trips after detecting over-current during running period. In case of Definite type, Over-current protection is provided by the relay tripping when motor operating current(In) exceeds EOCR current setting(Is) for a period greater than preset trip time(O-Time), while Inverse type shows that Over-current protection is provided by the relay tripping according to the Time-Current Characteristic Curve.

### RESET

Depressing the RESET button or interrupting power supply resets the relay immediately. Depress the RESET button on the facia for manual reset. Electrical Reset can be achieved by interrupting power supply in remote area. Auto Reset can be achieved automatically according to R-Time setting. Auto reset function is selectable by using mode switch. EOCR with fixed auto reset time or adjustable auto reset time is applicable.

### TEST

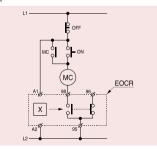
It has function to check and confirm the status of the motor by depressing the TEST button on the facia. To keep depressing the TEST button makes relay trip after the elapse of D-Time and/or O-Time. Once TEST is done, then reset the relay by depressing RESET button. The test function of Digital EOCR with 7 Segment Display cannot be performed during motor running, but possible when motor is stopped.

### N Type (Fail-safe Mode / No Volt Release)

NVR(No Volt Release)/On(N Type) Fail-safe

R type (Non-Fail-Safe Mode)

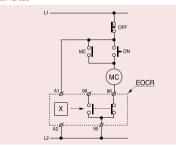
Non-Fail-safe



The output of relay is normally energized with control power applied. It is called NVR (No Volt Release) function and recommended to use output mode for safe protection. It is selectable by DIP switch or FS Mode

Caution) NVR function is designed to offer more accurate protection for motor. The motor can not start in case there is no power supply to EOCR or the span of life of motor is gone through. It is able to find the problem in its process in advance.

## NVR(No Volt Release)/Off (R Type)



In all case, the failure of the control voltage may not interrupt the process. It is selectable by DIP switch or FS Mode

Caution) In case of Non-Fail-Safe mode, periodical checking is required in case there is abnormal power supply to EOCR or the span of life of motor is gone through.

# **Digital EOCR**

Classification EOCR-3DE Series			EOCR-	3M Series			EOCR-FI	DE Series		EOCR-F	M Series		EOCR	R-P Seri		
	Model					251				Ferminal				Terminal		
	Model	3DE	3EZ	3DM	3MS	3MZ	3M42	20	FDE	FEZ	FDM	FMS	FMZ	FM420	PMZ	
Wiring	Wire-through	0	0	0	0	0	0		0	0	0	0	0	0	0	
wining	Terminal	-	-	-	-				0	0	0	0	0	0	0	
Mount	Flush Mounting	-	-	-	-	-		-	<ul> <li>(Display)</li> </ul>	-	<b>—</b>					
WOULIT	Panel Mounting	0	0	0	0	0	0	-	<ul> <li>(Converter)</li> </ul>	0	+					
	Basic Type	0.5-	-60A	05: 05~10A, 60: 5~70A	05: 05~10A, 20: 5~20A	05: 05~10A, 60: 5~70A	05: 05~10A, 6	60: 5~70A	0.5-	-60A	05: 05~10A, 60: 5~70A	05: 05~10A, 20: 5~20A	05: 05~10A, 60: 5~70A	05: 05~10A, 60: 5~70A	05	5~60A
	Overcurrent Use external CT	1~960A(1	10:5~800:5) 1~960A(10:5~800:5)				1~960A(10:5~800:5)		1~960A(10:5~800:5)			1~3600A	A(10:5~300			
	Undercurrent	0.5~less than preset O.C / OFF 0.5~less than preset O.C / OFF						0.5~less than p	reset O.C / OFF	0.5-less than preset O.C / OFF			0.5~less than	preset O.		
	Locked Running	0.5, 1-	-10sec		1~10sec				0.5, 1-	-10sec	1~10sec			OFF/0.1~10sec/Adju		
Ducto effect	Rotor Starting	Within 0.5se	after D-Time		Within 0.5sec after D-Time				Within 0.5sed	after D-Time	Within 0.5sec after D-Time				Within 0.5s	ec after D
Protection	Phase Loss	Withi	n 3sec		Within 3sec				Withir	n 3sec	Within 3sec				Witi	thin 3sec
	Phase Reversal	0.1~(	).3sec		0.	1sec			0.1~0	).3sec	0.1sec			0.1	~0.3sec	
	Phase Unbalance	Withi	n 8sec	Within 8sec					Withir	Within 8sec Within 1			Within 8sec			
	Ground Fault	-	A:0.02~3A, B:0.2~10A	-	-	A:0.03~2.5A, B:0.2~10A			-	A:0.02~3A, B:0.2~10A	-	-	A:0.03~2.5A, B:0.5~10A	-	Definite: 0.03~10	0A, Invers
	Short Circuit	-	-	-	0.05sec	-			-	-	-	0.05sec	-	-	0.03	3~0.05sec
Alert Outpu	ıt	A/F/H/U	-	A/F/H	-				A/F/H/U	-	A/F/H	-	-	-	-	
Trip Cause	Memory	Last 3 T	ip Cause		Last 1	Trip Cause			Last 3 Ti	ip Cause		Last 1 T	rip Cause		Last 3	Trip Caus
Trip Cause	Display	0	0	0	0	0	0		0	0	0	0	0	0	0	
Display		4-Digit 7	segment		5-Digit	7segment		-	4-Digit 7	segment		5-[	Digit		5	5-Digit
Running Ti	me Memory & Setting	-	-	0	0	0	0		-	-	0	0	0	0	0	
Bar-Graph		-	-	0	0	0	0		0	0	0	0	0	0	0	-
Current Sid	nal Output	-	-	-	-		4~20n	nA	-	-	-	-	-	4~20mA	4~	~20mA
Setting SW	. Type	Butto	n SW.		Rotary SW	& Button SW.			Butto	n SW.		Rotary SW.	& Button SW.		But	tton SW.
0	ult Current Sensing	-	Zero Phase Current	-	-	Zero Phase Current			-	Zero Phase Current	-	-	Zero Phase Current	-	Zero Ph	hase Curre
Orantaut	Mada	O.L:2-SPST(1a1b)	O.L:1-SPST(1a)	O.L:2-SPST(1a1b)	O.L:2-SPST(1a1b)	O.L:1-SPST(1a)	O.L:2-SPST	Г(1a1b)	O.L:2-SPST(1a1b)	O.L:1-SPST(1a1b)	O.L:2-SPST(1a1b)	O.L:2-SPST(1a)	O.L:1-SPST(1a)	O.L:2-SPST(1a1b)	OL/SH : 2	2-SPST(1:
Contacts	Mode	AL:1-SPST(1a)	GR:1-SPST(1a)	AL:1-SPST(1a)	S.C:1-SPST(1a)	GR:1-SPST(1a)			AL:1-SPST(1a)	GR:1-SPST(1a)	AL:1-SPST(1a)	SC:1-SPST(1a)	GR:1-SPST(1a)	-	GR : 1	1-SPST(1a
Rating	Rating	3A/250VA	C, Resistive		3A/250VA	AC, Resistive			3A/250VA	C, Resistive		3A/250VA	C, Resistive		3A/250V	/AC, Resis
Control Vo	tage (50/60Hz)	24VAC/DC, 220VAC	± 15%, 110VAC ± 15%		24VAC/DC, 8	85~250VAC/DC			24VAC/DC, 220VAC ±	15%, 110VAC ± 15%		24VAC/DC, 8	5~250VAC/DC		24VAC/DC,	85~250V
	• • •			1												

#### • Panel Mounting / Flush Mounting makes it easier for use.

- Digital Ammeter is installed at the front cover of panel door in Flush Mounting type. It makes possible to check sensing current and finding the cause of trip with tripped current easily, to set current and O-time by simple button selection without removing unit from panel. - Panel Mounting type with Digital Ammeter is installed inside the MCC panel and Just Operator is Possible to adjust it.

### Following conditions should be considered in case of installing EOCR.

Overcurrent & Phase Loss must be included as basic protective function in the point of view for its law and regulation.

- Earth leakage current protection must be added against moisture and humidity conditions.
- In case you need to sense the overload increasing, Alert function must be added. - If you need to confirm the current of many motors in one place , Current signal output transducer function (4~20mA) must be added.

- Short Circuit protection must be added if you protect line damage caused by Short Circuit.

- EOCR with 3CT is recommended to not only 3 Ø 3w, but also 3 Ø 4w condition.
- Window / Terminal makes it easier for installation.

- Wire is passing through CT without cutting, that is much easier for installation. It has also more convenient application to external CTs.

- As for Terminal type, display part is Flush Mounting type but Converter is Panel Mounting type with its application less than 60Amp.

• The same diameter of Digital Ammeter to conventional Analogue Ammeter makes it easier for installation. - Ammeter Selector S/W is not necessary as 3 phase current is displayed L1, L2, L3 in order every 5 seconds.

It is easy to install Ammeter by using cap cover and it saves install time.

Alert Output Mode

- "A" (Ampere Relay): Energized when sensing current - "H" (Holding): ON-OFF output mode

## 3

- "F" (Flicker): Flicker

- "U" (Under Current Mode): "AL" oupput is transferred to UC (3DD/FD vesion "E")

#### CR-3DE/FDE EO

#### • M( CU Based

- Re al Time Processing / Higher Precision
- Ov recurrent Protection Range: 0.5~60A, Wide Range Protection (Use with external CT from 11 to 960A, Direct application without CT up to 60A)
- Indercurrent Protection Range: 0.5~59A / OFF (Use with external CT less than 960A) • Un
- Tin ne Characteristic for Overcurrent
- 5~10A : Definite / Inverse Selectable, Over 11A : Definite(Use with external CT in case using Inverse time) - 0.5
- "U C" output is used as common to "OC" output. When choosing "U" in ALo mode, "AL" mode becomes
- OFF F(--) and AL output ( 07-08 ) is transferred into Undercurrent (UC) output mode automatically.
- gital display / 3 Phase Current Display: Digital Ammeter (Every 5 seconds) • Diç
- pped Cause Digital Display: Easy Troubleshooting / Trij
- Tri ip Cause Memory: Last 3 trip check function. Possible to check with tripped trip cause and current
- anual / Electrical Reset • Ma
- Th e tripping relay is normally energized with control power supply. (Selectable)
- Fit to a variety of environment as Terminal & Window type.
- sistive Strengthened against variable frequency device such as inverter : 20~400Hz. • Re



### **EOCR-SSD** erload Relav

## **Digtal Over-Current Relav**

Series



0

0

~3000:5)

et O.C / OFF Adjustable

ter D-Time

verse: 0.03~1A

-

0 0 0

Sec

sec

sec

5sec

Cause

A SW. Current ST(1a1b) ST(1a) Resistive 250VAC/DC

(Display)

(Converter)



### Protection

Protective Item	Trip Time	Description		
Over-current	O-Time	ls <ln< th=""></ln<>		
Phase Loss	3sec	[(MAX - MIN) / MAX] × 100>90		
Locked Rotor	0.5sec after elapse dt	≥ 3times OC setting value		

### Specification

Over-current Setting	Current	05	0.5 ~ 6A		
		30	3 ~ 30A		
		60	10 ~ 60A		
	Starting delay time	D-Time	1 ~ 30sec		
	Trip time	O-Time	0.5, 1 ~ 10sec		
Reset			Manual / Electrical		
Operating t-c character	istic	Over-current	Definite		
Tolerance		Current	I<1A : ± 0.05A, I ≥1A : ± 5%		
		Time	t ≤3S : ±0.2s, t>3s : ±5%		
Environment	Temperature	Operation	-20°C ~60°C		
		Store	-30°C ~80°C		
	Humidity		30~85% RH non-condensing		
Control Power			<ul> <li>110 : 110VAC ± 15%, 50/60Hz</li> </ul>		
			<ul> <li>220 : 220VAC ± 15%, 50/60Hz</li> </ul>		
			<ul> <li>440 : 440VAC ± 15%, 50/60Hz</li> </ul>		
			• 24 : 240VAC/DC		
Contact Rating		2-SPST	3A / 250VAC , Resistive		
Insulation	Between casing and	circuit	Over 10 №, DC500V		
Dielectric Strenghth	Between casing and	circuit	2000VAC 60Hz, 1min		
	Between open conta	icts	1000VAC 60Hz, 1min		
	between circuit		2000VAC 60Hz, 1min		
Installation			35mm Din Rail or Panel Mounting		

### MCU(Micro Controller Unit) based / 2-CT Type

- Real Time Processing / Higher Preceision
- Current Setting Renge 05Type : 0.5 ~ 6A / 30Type : 3 ~ 30A / 60Type : 10 ~ 60A
- Digital display : trip cause / easy troubleshooting
- Reset : Manual (instantaneous) / Electrical (remote)
- Load selection by DIP switch : Single phase(1P) / Three phase(3P)
- Fail safe(N) / Non-fail safe(R)

# **EOCR-3DM/FDM Series**

### Digital Over Current Relay

Features

- Compact Design
- 3DM : Panel Mounting Type • FDM : Flush Mounting Type
- MCU(Microprocessor Control Unit) & ASIC Based
- 3 Integral Current Transformers
- Multiple Protection Functions
- Digital Ammeter
- Troubleshooting / Trip Cause Memory, Display
- Adjustable Operating Features by Pulse Rotary switch
- Wide Current Adjustment Range
   Selectable Time-Current Characteristics (Inverse / Definite)
- Manual Instantaneous / Electrical Remote Auto Reset
- Test Function
- Ambient Insensitive
- Selectable Fail-safe and Non-fail-safe Operation Modes

### **Comparison Table of Model**

EOCR		3DM / FDM	3MZ / FMZ
Protection	Over - current	•	•
	Under - current	•	•
	Phase Loss	•	•
	Phase Unbalance	•	•
	Phase Reverse	•	•
	Locked Rotor	•	•
	Ground Fault	-	•
Run Monitor & Load	Alert Function	•	-
Selectable Alerting P	ulse	•	

### Protection Feature

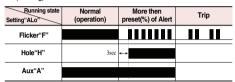
Function	DIP Switch	Description
Over	DEF sw#3 on	When motor operating current(In) exceeds preset "oc"setting, relay will trip after preset O-Time in "of"setting. The amperage of In(operating current) does not effct on relay trip time.
	INV sw#3 off	The tripping time of relay depends on the amperage of In(operating current) according to time-current charateristics
Under current	Definite time charateristic	This is for idle/dry running protection The relay operates when the operating current is less than preset "uc" current after preset "ut" time elapses.
Phase Loss		The relay will be operated within 3sec. when the phase failure occurs This function works during D-Time.
Phase Unbalance		The relay operates within 8sec. when the current diffenence among 3 phases is greater than 50% The calculation formula is(Max-Min)Max current 100 $\rangle$ 50%
Phase Reversal	on : enable off : disable	In the event of wrong phase sequence, relay will be operated in 0.1sec. Phase reversal protection function can be disabled by DIP selection.
Ground Fault	A Type: 0.03-2.5A B Type : 0.5-10A	Ground fault protection is provided by the relay tripping sensed by Zero Phase Current Transformer (Core Balanced Current Transformer) The relay shows the leakage current during operation (3MZ & FMZ)
Locked Rotor		The setting range is 2-10 times of oc setting. If the starting current exceeds more than setting value after preset D-Time elapses, the relay will be energized within 0.5sec. This function is available on definite time characteristic.
Stall		The setting range is 1-10sec. If the operating current exceeds more than 180% of preset "oc" setting the relay will be energized after preset "st" time elapses.

### Looping & External CT Option Refer to page 10

### Alert Function : 3DM & FDM

When motor operating current (In) exceeds the alert setting (As), the alert relay outputs three kind of signal. The output can be used to warn customers/operators of possible overloading and avoid unnecessary motor shutdown

The type of output signal is decided by the selection in the "Alo" mode "A" (Ampere relay): energized whenever CT senses a current "F"(Flickering): character"A" and current value flash frequently "H"(Holding): ON-OFF



In = Motor Operating Current / Is = EOCR Over-current Setting / As = Alert Setting

### Fail-safe & Non-fail-safe

The tripping relay can be operated in a fail-safe or non-fail-safe mode

Application of the Fail-safe (Electrically Held) Connection Faie safe setting in NVR mode : ON

The tripping relay is normally energized with control power supply

### Application of the Non-fail-safe Connection

Fail safe setting in NVR mode: OFF In all cases, the failure of the control voltage may not interrupt the process.

	Contr	ol power on→	Ralay Trip→	
FS:ON	95 <del>1</del> - F96			
(Fail safe)	97-   -98			
FS (OFF)	95 <del>1</del> /-96			
(Non-Fail safe)	97-   -98			

* Tolerance (3DM/ FDM	1 / EVR Series)
Current	I<1A : ±0.1A I≥1A : ±5%
Time	0.05s → Within 0.05s t<1s :±0.1s t≥1s :±5%

# **EOCR-3DM/FDM Series**

### Digital Over Current Relay

LED Display

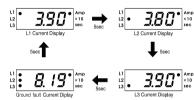


### **Digital Ammeter**

3 phase motor currents (In) are displayed in sequence on the LED display.



3MZ/FMZ



### Digital Trip Cause Indication / Easy Troubleshooting

 Enter into "FAULT" mode with mode switch by depressing once Set/store button, then last trip cause is shown
 Each phase current is displayed in order whenever turn mode

switch right or left

### Test

This is the self-test of this product. If the relay enters into this mode, it begins its count down preset value of O-time of "Ot" mode after waiting 3sec and becomes trip state as showing "END" message that means this relay is ready to work.

- "END" message of a result of this test is also stored in "Fault" mode as last trip.
- Not permitted to test this function during the operation to prevent unnecessary trip

### Reset

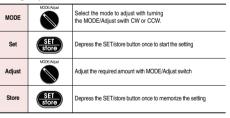
Pushing the RESET button or interrupting power resets the relay immediately. Electrical remote reset is also available through the panel mounted reset switch. The relay cannot be reset by control power interruption when the hand reset (H-r) selected in mode. In this case, it is possible to press the reset button on the relay facia. Automatic reset is also available if enter into reset mode (rt:A-r) and reset delay time is adjustable from 0.3sec to 20min

Examples	of Trip	Cause	Indication

Examples of http stade indication	
Over-current Trip Relay displays a trip, caused by maximun over-current. 10.7A which has been detected from phase L3(T/T3)	L1 L2 L3 L3
Under-current Trip Relay displays a trip, caused by minimum Under-current. 1.14A which has been detected from pfase L2(S/T3)	L1 L2 L3 L3 L1 L2 L3 L3 L3 L1 L2 L3 L1 L2 L1 L2 L1 L2 L1 L2 L2 L1 L2 L2 L2 L2 L2 L2 L2 L2 L2 L2 L2 L2 L2
Locked Rotor Trip Relay displays a trip, caused by locked rotor and maximum current. 26.9A which has been detected from plase L1(R/T1)	L1 L2 L3 <b>*L 25.9*</b> Amp sec
Locked Rotor Trip Relay displays a trip, caused by locked rotor while motor is working	L1 L2 L3 <b>528LL</b> Amp ×10 Sec
Phase reversal Trip     Relay displays a trip, caused by phase reversal	L1 L2 L3 - <b>A</b> mp ×10 Sec
Phase Unbalance Trip Relay displays a trip, caused by Phase unbalance and maximum current 2.78A which has been detected from phase L1(R/T1)	L1 L2 L3 U 2.78 Amp ×10 Sec
Phase Loss Trip Relay displays a trip, caused by phase loss which has been detected from phase L1(R/T1)	L1 L2 L3 <b>PL</b> Amp ×10 Sec
Phase Loss Trip Relay displays a trip, caused by phase loss which has been detected from phase L2(S/T2)	L1 L2 L3 • <i>PL</i> - 5 <sup>Amp</sup> Sec
Phase Loss Trip Relay displays a trip, caused by phase loss which has been detected from phase L3(T/T3)	L1 L2 L3 <b>PL - L</b> Amp ×10 Sec
Ground Fault Trip     Relay displays a trip, caused by ground fault current 0.6A which has been detected from ZCT	L1 L2 L3 E 0.5 Sec

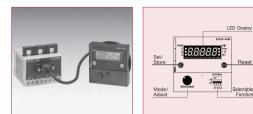
Time-Current Characteristic Curve Refer to Curve-1 and Curve-2 on page 11

### Setting Step of 3DM & FDM



# EOCR-FDM/FMS/FMZ/FM420

## MCU & ASIC Based Overload Relay



- Over-current, Under-current, Phase Loss, Phase reversal, Phase Unbalance, Locked rotor protection
- Short current protection ← FMS
- Ground Fault Protection  $\leftarrow$  FMZ
- Current Loop Commeunication ← FM420
- Including Current Tranducer : 4~20mA output
   Accummulation to Running time

EOCR-FDM / FMS / FMZ / FM420

### Protection

			Trip Time					
Protective Item		FDM	FMS	FMZ	FM420			
Over-current		DEF: 0.2 ~ 30sec, INV: 1 ~ 30	DEF: 0.2 ~ 30sec, INV: 1 ~ 30	DEF: 0.2 ~ 30sec, INV: 1 ~ 30	DEF: 0.2 ~ 30sec, INV: 1 ~ 30			
Under-Current		0.5 ~ 30sec(DEF)	0.5 ~ 30sec(DEF)	0.5 ~ 30sec(DEF)	0.5 ~ 30sec(DEF)			
Phase loss		3sec	3sec	3sec	3sec			
Phase reversal		0.1sec	0.1sec	0.1sec	0.1sec			
Phase Unbalance		8sec	8sec	8sec	8sec			
Locked Roter	Lock	0.5sec after dt	0.5sec after dt	0.5sec after dt	0.5sec after dt			
	stall	1 ~ 10sec	1 ~ 10sec	1 ~ 10sec	1 ~ 10sec			
Ground fault		-	-	0.1 ~ 10sec	-			
Short circuit			0.05sec	-				

### Specification

Model			FDM	FMS	FMZ	FM420
Current Setting	Over-Current(o	c)	Refer to, Table #1	Refer to, Table #1	Refer to, Table #1	Refer to, Table #1
Range	Under-Current(	uc)	0.5 ~ under OC setting	0.5 ~ under OC setting	0.5 ~ under OC setting	0.5 ~ under OC setting
-	Ground Fault C	urrent(Ec)	-	-	A: 0.03 ~ 2.5A / B: 0.5 ~ 10A	-
Time Setting	Starting Delay 1	F ime(dt)	OFF ~ 200sec	OFF ~ 200sec	OFF ~ 200sec	OFF ~ 200sec
	Over-Current T	rip Delay(ot)	DEF : 0.2 ~ 30sec / INV : 1 ~ 30	DEF : 0.2 ~ 30sec / INV : 1 ~ 30	DEF: 0.2 ~ 30sec / INV : 1 ~ 30	DEF: 0.2 ~ 30sec / INV : 1 ~ 30
	Under-Current	Trip Delay(ut)	0.5 ~ 30sec(DEF)	0.5 ~ 30sec(DEF)	0.5 ~ 30sec(DEF)	0.5 ~ 30sec(DEF)
	Ground Fault T	rip Delay(Et)	-	-	0.1 ~ 10sec	-
Short circuit			-	0.05sec	-	-
Control Power 24			24VAC/DC	24VAC/DC	24VAC/DC	24VAC/DC
	220		85 ~ 250VAC/ DC, 50/60Hz	85 ~ 250VAC/ DC, 50/60Hz	85 ~ 250VAC/ DC, 50/60Hz	85 ~ 250VAC/ DC, 50/60Hz
Contact Rating	OL		2-SPST, 3A/250VAC, Resistive	2-SPST, 3A/250VAC, Resistive	1-SPST, 3A/250VAC, Resistive	2-SPST, 3A/250VAC, Resistive
	AL(GR/SC)		1-SPST(AL)	1-SPST(S.C)	1-SPST(GR)	-
Environment	Temperature	Store	-30°C ~ 80°C	-30°C ~ 80°C	-30°C ~ 80°C	-30°C ~ 80°C
		Operation	-20°C ~ 60°C	-20°C ~ 60°C	-20°C ~ 60°C	-20°C ~ 60°C
	Humidity		30 ~ 85RH, Without condensation	30 ~ 85RH, Without condensation	30 ~ 85RH, Without condensation	30 ~ 85RH, Without condensation
Display	7-Segment LED	Ds	0	0	0	0
	Bar-Graph		0	0	0	0
Mounting			35mm Din-rail	35mm Din-rail	35mm Din-rail	35mm Din-rail

Table #1. Current Range : Same as Table#1 on page 16

Caution : The external CT should be used in case Inverse curve(toln setting) is applied over 10Amps.